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Correction série 4: Motor asynchrone

Exo 1:

motor 230V/400V

1°/

a)

réseau 120/230V - 50Hz

$U_{\text{mot}} = 230V = U_{\text{réseau}} \Rightarrow$ couplage triangle

b)

réseau triphasé 230/400V

$U_{\text{mot}} = \frac{U_{\text{réseau}}}{\sqrt{3}} = 230V \Rightarrow$ couplage étoile

2°/ a) Puissance: $P_a = U I \sqrt{3} \cos \phi$

$$P_a = 400 \cdot I \times 0,78 \times \sqrt{3} = \frac{P_M}{\eta} = \frac{15}{0,88}$$

↓

$$P_a = 18,75 \text{ kW}$$

b)

$$I = \frac{P_a}{U \sqrt{3} \cos \phi} = \frac{18750}{400 \sqrt{3} \times 0,78} = 34,7 \text{ A}$$

c)

$$n_s = \frac{f}{p} = \frac{50}{p} = \frac{3000 \text{ tr/min}}{p}$$

p	1	2	3	4
n_s (tr/min)	3000	1500	1000	750

$n < n_s \Rightarrow$

$n_s = 1500 \text{ tr/min}$

pour $n = 1430 \text{ tr/min}$

et $p = 2$

glissement: $g = \frac{n_s - n}{n_s} = \frac{1500 - 1430}{1500}$

$$g = 4,66\%$$

d°/

$$T_M = \frac{P_M}{\Omega} = \frac{15000}{2\pi \cdot \frac{n}{60}} = \frac{15000 \times 9,55}{1430}$$

$$T_M = 100,2 \text{ Nm}$$

$$\frac{2\pi}{60} = \frac{1}{9,55}$$

2

Exo 2

1°/ $n_s = \frac{f}{p} = \frac{50}{3} = 16,67 \text{ tr/s} = 16,67 \times 60 \text{ tr/min}$

$n_s = 1000 \text{ tr/min}$

2°/ moteur: 400V/660V
réseau: 230V/400V
 $U_{\text{mot}} = U_{\text{réseau}} \Rightarrow$ coupage triangle

3°/

a) $J = 10 \text{ A}$

b) $I = 17,3 \text{ A}$ coupage triangle
($J = 10 \text{ A}$ coupage Δ)

4) $P_a = U I \sqrt{3} \cos \varphi = 3 U J \cos \varphi$

$P_a = 3 \times 400 \times 10 \times 0,8 = 9,6 \text{ kW}$

5°/ $P_{JS} = \frac{3}{2} R I^2 = \frac{3}{2} \times 1,5 \times 17,3^2$

$P_{JS} = 673,4 \text{ W}$

6°/ $P_M = P_a - P_{JS} - P_{\text{pert}} = 9600 - 673 - 833$

$P_M = 8094 \text{ W}$

$T_M = \frac{P_M}{\omega} = \frac{8094}{2\pi \cdot \frac{n}{60}} = \frac{8094}{2\pi \times \frac{960}{60}} = 80,5 \text{ Nm}$

$T_M = 80,5 \text{ Nm}$

Exercice 3

1°/ $P_a = U I \sqrt{3} \cos \varphi = 660 \times 10 \times \sqrt{3} \times 0,8$

$P_a = 8916 \text{ W}$

2°/ $P_{JS} = 3 R_s I^2 = 3 \times 1,8 \times 10^2 = 480 \text{ W}$

3°/ $P_{\text{tr}} = P_a - P_{JS} - P_{\text{FS}} = 8916 - 480 - 470$

$P_{\text{tr}} = 7966 \text{ W}$

③ 4°/ $n_s = \frac{f}{p} = \frac{50}{4} = 12,5 \text{ tr/s} = 750 \text{ tr/min}$

il y a 8 poles $\Rightarrow p=4$

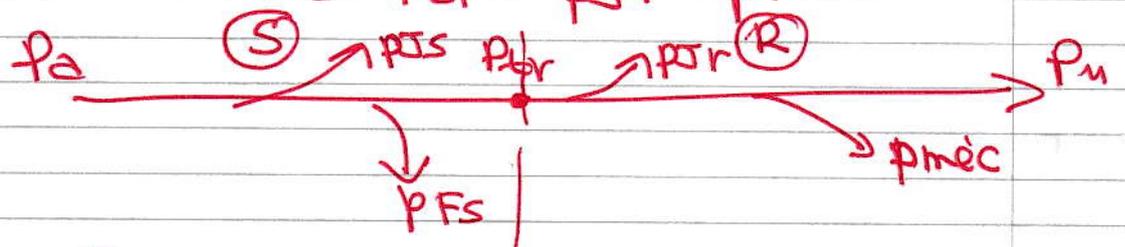
$g = \frac{n_s - n}{n_s} = \frac{750 - 720}{750} = 0,04$

$g = 4\%$

5°/ $P_{tr} = g \times P_{tr} = 0,04 \times 7966$

$P_{tr} = 319 \text{ W}$

6°/ $P_m = P_{tr} - p_{tr} - p_{mec}$



$P_m = 7966 - 319 - 330 = 7317 \text{ W}$

$T_m = \frac{P_m}{\omega} = \frac{7317}{2\pi \frac{n}{60}} = \frac{7317}{2\pi \times \frac{720}{60}} = 9,7 \text{ Nm}$

7°/ $\eta = \frac{P_m}{P_a} = \frac{7317}{8916} = 82\%$

8°/ $\cos \varphi = 0,96$

la nouvelle puissance réactive ?

$Q' = Q \times \tan \varphi' \Rightarrow$ on calcule Q'

$(Q = P \times \tan \varphi) \quad \varphi = \cos^{-1}(0,96)$

$\Rightarrow Q' = Q + Q_c \Rightarrow Q_c = Q' - Q$

$Q_c = 3U^2 C_D \omega \Rightarrow C_D = \frac{Q_c}{3U^2 \omega}$

$C_D = \frac{P \times (\tan \varphi - \tan \varphi')}{3U^2 \omega} = \frac{8916 \times (\tan \varphi - \tan \varphi')}{3 \times 660^2 \times 314}$

$\varphi = \cos^{-1}(0,96), \quad \varphi' = \cos^{-1}(0,96)$

$C_D = 11 \mu\text{F}$

9°/ $I_2 = \frac{P_a}{\sqrt{3} \cos \varphi} = \frac{8916}{660 \times \sqrt{3} \times 0,96} = 8,12 \text{ A}$